NATIONAL UNIVERSITY OF SCIENCE AND TECHNOLOGY FACULTY OF APPLIED SCIENCE

COMPUTER SCIENCE DEPARTMENT **DECEMBER EXAMINATIONS 2001**

SUBJECT: DIGITAL SIGNALS PROCESSING CODE:

SCS 6101

INSTRUCTION TO CANDIDATES

Answer any four (4) questions. Each question carries 25 marks



Time: 3 hours

QUESTION ONE

- What are the classification of Discrete-time systems and distinguish a) between them. [8]
- Test whether the following Discrete-time signals are periodic, if it is b) periodic find its fundamental period. [5]

 $x(n) = 5\sin(2n)$

- Find whether the system y(n) A x(n) + B is c)
 - i) Linear
 - Time invariant ii)
 - iii) Casual
 - iv) Stable

[12]

QUESTION TWO

- Write the expressions for a)
 - i) An arbitrary discrete time signal x(n) resolued into Impulses.[1]
 - ii) Linear convolution.

Graphical representation of the following discrete time signal. iii)

$$x(n) = (-2)^n u(n)$$

[2]

Convolve the sequences given

$$h(n) = S(3)^{\widehat{\omega}} h(n) \xrightarrow{S_1 \times S_2 \times S_3} 1$$

$$x(n) = 4(-2)^n u(n)$$
[11]

Find the DFT of the sequence

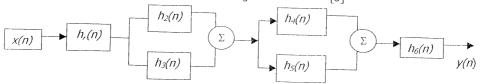
$$x(n) = \{1, 2, 2, 1\}$$
 [10]

QUESTION THREE

i) An LTI system has the Impulse response $h(n) = \left(\frac{3}{4}\right)^n u(n)$. Determine the output of the system at times n=-5, n=+5 and n=10 when input x(n)=u(n)

[10]

ii) Find the expression for impulse response relating to input x(n) or x(t) to the output y(n) or y(t) in terms of the impulse response of each subsystem for the LTI system depicted in fig. Below. [3]



b) Let $h_1(t)$, $h_2(t)$, $h_3(t)$ and $h_4(t)$ be the impulse responses of LTI system construct a system with impulse response h(t) using $h_1(t)$, $h_2(t)$, $h_3(t)$ and $h_4(t)$ as sub-system. Draw the interconnection of systems required to obtain

$$h(t) = h_1(t) \times h_2(t) + h_3(t) \times h_4(t)$$
 [3]

c) Define the elementary signals $\delta(t)$, u(t) and r(t) and bring out the relation between them.

Define stability of a system.

[3]

MODEL CATALON

UESTION FOUR

- What are FIR and IIR systems. Give examples. 3)
 - Bring out the advantages of FIR filter compared to IIR filters. ii)

[5]

A discrete time system has a unit sample response h(n) given by b)

$$h(n) = \frac{1}{2}\delta(n) + \delta(n-1) + \frac{1}{2}\delta(n-2)$$
 [15]

Find the frequency response $H(e^{i\omega})$. Plot its magnitudes phase.

Find the convolution of the below finite sequence: c)

$$x(k) = \{ \frac{1}{2}, 2, 1, -1 \}$$

$$h(k) = \{ 2, 1, \frac{1}{2} \}$$
[5]

QUESTION FIVE

- a) Briefly explain
 - i) aliasing
 - ii)
 - Determine the sampling frequency for the following signals

$$x(t) = Sin200\Pi t + Cos300\Pi t + Sin400\Pi t$$
 [6]

Find the circular convolution of the following two secuences b)

$$x(n) = \{0, 1, 2, 3\}$$
 \uparrow
 $h(n) = \{2, 1, 1, 2\}$
 \uparrow

Realize the following transfer function as Direct form I and II structure

$$H(z) = \frac{8z^3 - 4z^2 + 4z - 2}{(z - \frac{1}{4})(z^2 - z + \frac{1}{2})}$$
 [12]

QUESTION SIX

With the help of block diagrams, explain how DSP techniques can be used for any one application. [25]

END OF QUESTION PAPER

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